

Test Waiting...

<Idle,MPos:0.000,0.000,0.000,WPos:0.000,0.000,0.000,Buf:0,RX:0,Ln:0,F:0.>

gc\_not\_motion

\$

\$0=10 (step pulse, usec)  
\$1=255 (step idle delay, msec)  
\$2=0 (step port invert mask:00000000)  
\$3=6 (dir port invert mask:00000110)  
\$4=0 (step enable invert, bool)  
\$5=0 (limit pins invert, bool)  
\$6=0 (probe pin invert, bool)  
\$10=255 (status report mask:11111111)  
\$11=0.020 (junction deviation, mm)  
\$12=0.010 (arc tolerance, mm)  
\$13=0 (report inches, bool)  
\$14=1 (auto start, bool)  
\$20=0 (soft limits, bool)  
\$21=0 (hard limits, bool)  
\$22=0 (homing cycle, bool)  
\$23=0 (homing dir invert mask:00000000)  
\$24=100.000 (homing feed, mm/min)  
\$25=1000.000 (homing seek, mm/min)  
\$26=25 (homing debounce, msec)  
\$27=5.000 (homing pull-off, mm)  
\$100=40.000 (x, step/mm)  
\$101=40.000 (y, step/mm)  
\$102=40.000 (z, step/mm)  
\$110=5000.000 (x max rate, mm/min)  
\$111=5000.000 (y max rate, mm/min)  
\$112=5000.000 (z max rate, mm/min)  
\$120=400.000 (x accel, mm/sec^2)  
\$121=400.000 (y accel, mm/sec^2)  
\$122=400.000 (z accel, mm/sec^2)  
\$130=425.000 (x max travel, mm)  
\$131=465.000 (y max travel, mm)  
\$132=80.000 (z max travel, mm)  
ok

gc\_dwell

N0 G4P0.05

<Idle,MPos:0.000,0.000,0.000,WPos:0.000,0.000,0.000,Buf:0,RX:0,Ln:0,F:0.>

ok

gc\_get\_offsets

\$

<Idle,MPos:0.000,0.000,0.000,WPos:0.000,0.000,0.000,Buf:0,RX:0,Ln:0,F:0.>  
[G54:0.000,0.000,0.000]  
[G55:0.000,0.000,0.000]  
[G56:0.000,0.000,0.000]  
[G57:0.000,0.000,0.000]  
[G58:0.000,0.000,0.000]  
[G59:0.000,0.000,0.000]  
[G28:0.000,0.000,0.000]  
[G30:0.000,0.000,0.000]  
[G92:0.000,0.000,0.000]  
[TLO:0.000]  
[PRB:0.000,0.000,0.000:0]  
ok

gc\_parser\_state

\$G

[G0 G54 G17 G21 G90 G94 M0 M5 M9 T0 F0. S0.]

ok

<Idle,MPos:0.000,0.000,0.000,WPos:0.000,0.000,0.000,Buf:0,RX:0,Ln:0,F:0.>