## DELIXI

## **CDI-EM60 Series Frequency Inverter Operation Manual**

Product standard: GB/T 12668.2-2002 GB 12668.3-2003

☐ Before the product is installed and used, please thoroughly read the Manual and keep it well.



## 2.2 Technical specification

Item		Specification			
	Control mode	V/F control			
Control	Control mode	Open-loop vector control (SVC)			
	Engine av Desclution	Digital: 0.02%			
	Frequency Resolution	Analog: 0.1%			
	V/F curve	Linear, square root, random V/F			
	Overload capability	150% rated current 60s; 180% rated current 3s			
	Start torque	G type: 0.5Hz/150% (SVC);			
	Speed Regulation	1:100 (SVC)			
	Range				
	Stable Speed Accuracy	(±0.5% (SVC)			
	T di	Manual torque compensation (0.1%-30.0%), automatic torque			
	lorque compensation	compensation			
	Control power supply	Max. output current 300mA			
	+24V				
		The 4-way Digital Input Terminal (DI1-DI4) can be additionally			
	Input terminal	expanded by 2-way (DI5-DI6) through connecting with the IO			
		expansion card, DI6 can be connected with the high speed impulse input			
		1-way analog input terminal (VF1) which can be additionally expanded			
		by 1-way (VF2) through connecting with the IO expansion card, and it			
		can be also used as digital input terminal via setting.			
Configuration		Operating instruction: VF1 can serve as the voltage (0V-10V) or			
		current (0/4mA~20mA) input, however, VF2 can only serve as			
		voltage (0V~10V) input.			
		The 1-way Analog Output Terminal FM1 can be additionally expanded			
	Output terminal	by 1-way (FM2) through connecting with the IO expansion card, both			
		the voltage (0V-10V) and current ( $0mA \sim 20mA$ ) can be output, the			
		1-way relay outputs T1, below 30V/1A for DC and below 250V/3A for			
		AC.			
	Mode of operation	Keyboard, terminal, RS485 communication			
	<b>i</b>	14 main frequency sources, 14 auxiliary frequency sources. They can be			
	Frequency source	combined and switched via multiple modes. The input mode of each			
		frequency source can adopt multiple ways: keyboard potentiometer.			
		external analog, digital reference, impulse reference. Multiplex			
		Directive, simple PLC, communication, arithmetic results, etc.			
		14 kinds of Torque Sources, including digital reference, external analog.			
	Torque source	impulse reference. Multiplex Directive, communication, arithmetic			
		results, etc.			
	Acceleration and	4-group straight line (terminal switch can be selected via acceleration			
	Deceleration Time	and deceleration time). S curve 1 and S curve 2.			
Operation	Emergency stop	Interrupt frequency inverter output instantly			
		16-phase speed is allowable to set at most and use various combination			
	Multiplex Speed	of multiplex directive terminal to switch			
	Simple PLC function	Continuously run 16 phase speed and independently set acceleration			
		and deceleration time and running time			
		Independently set logging frequency and logging acceleration and			
	Logging Control	deceleration time, additionally, set the unit under running state and			
	Jogging Control	confirm whether the jogging is preferential			
	Potating Snood Treating	Fraguency inverter starts operation by tracking the load speed			
	Fixed longth	Paglize fixed length and fixed distance control function through			
	Fixed-length and	Realize lixed-length and lixed-distance control function through			
	inxed-distance control	impulse mput			

5.1 Group P0 - Basic Function							
Function code	Function name	Setting scope	Factory value	Modification limit	Reference page		
Group P0.0: Basic Group							
P0.0.00	Type of Frequency inverter	<ol> <li>G type (constant torque load type)</li> <li>P type (air-blower, water pump load type)</li> </ol>	Machine type	0	58		
P0.0.01	Display mode	<ul> <li>0: Primary mode (prefix is "P")</li> <li>1: User mode (prefix is "U")</li> <li>2: Check mode (prefix is "C")</li> </ul>	0	47			
P0.0.02	Control mode	0: V/F control 1: Open-loop vector control 2: Reserved	0	*	- 59		
P0.0.03	Option of operation control mode	0: Keyboard control (1: Terminal control) 2: Communication control	0	47			
P0.0.04	Option of A Frequency Source	0: Keyboard Reference (No Power-off Memory) 1: Keyboard Reference (Power-off Memory) 2: Keyboard Potentiometer Reference 3: External Terminal VF1 Reference 4: External Terminal VF2 Reference 5: PULS Impulse Reference (DI6) 6: Multiplex Directive Reference 7: Simple PLC Reference 8: PID Control Reference 9: Communication Reference 10: Operation Result 1 11: Operation Result 2 12: Operation Result 3 13: Operation Result 4	02	*	60		
P0.0.05	Keyboard Frequency Reference	000.00~Highest Frequency	050.00	\$7	61		
P0.0.06	Running Direction	<ul><li>0: Default Direction</li><li>1: Negation of Direction</li><li>2: Determined by multi-functional input terminal</li></ul>	0	*			
P0.0.07	Max. frequency	050.00Hz~320.0Hz	050.00	*	62		
P0.0.08	Upper limit frequency	Lower limit frequency ~ Max. frequency	050.00	*			
P0.0.09	Lower limit frequency	000.00~Upper limit frequency	000.00	$\stackrel{\wedge}{\sim}$			
P0.0.10	Lower frequency operation mode	0: Running at lower limit frequency 1: Stop 2: Zero-speed Running	0	*	63		
P0.0.11	Acceleration time	0000.0~6500.0s	Machine type	4	05		
P0.0.12	Deceleration time	0000.0~6500.0s	Machine type	$\Delta$			